

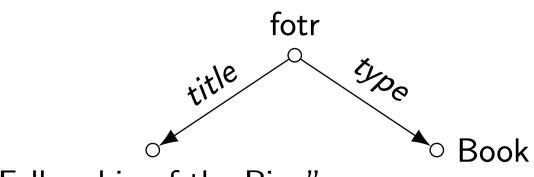
SHACL

- Shapes Constraint Language
- Constraint language for RDF graphs
- Conformance checking

:BookShape a sh:PropertyShape; sh:path :title; sh:minCount 1.

:BookShape sh:targetClass:Book.

 $\geq_1 type.Book \subseteq \geq_1 title. \top$



"Fellowship of the Ring"

Shapes

Let *N*, *P* and *S* be disjoint universes of node names, property names and shape names.

$$\phi \coloneqq \top \mid \{c\} \mid s \mid \phi \land \phi \mid \phi \lor \phi \mid \neg \phi \mid \forall E. \phi \mid \geq_n E. \phi$$

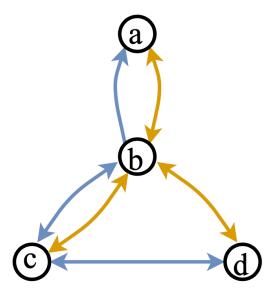
$$\mid eq(E,p) \mid disj(E,p) \mid closed(Q)$$

$$E \coloneqq p \mid p^- \mid E \cup E \mid E/E \mid E^* \mid E?$$
 where $c \in N, p \in P, s \in S$ and $Q \subseteq P$

E are regular path queries with inverse and zero-or-one paths

Example shapes

- "Through a path of **friend** edges, the node can reach node d"
 - $\phi \equiv \geq_1 friend^*.\{d\}$
 - b, c, and d satisfy ϕ in G
- "Nodes where friendship is mutual"
 - $\phi \equiv eq(friend, friend^-)$
 - c and d satisfy ϕ in G
- "Nodes who have at least one colleague who is also a friend"
 - $\phi \equiv \neg disj(friend, colleague)$
 - b and c satisfy ϕ in G





Shape schemas

The main task is to check whether a **graph** conforms to some constraints, not single nodes.

A shape definition is a statement of the form: $s \leftarrow \phi$

A shape schema consists of shape definitions and inclusion statements

$$\phi_t \subseteq \phi_s$$

SHACL allows only the following target shapes ϕ_t :

- Node targets: $\{c\}$
- Class-based targets: \geq_1 subclassOf*. \geq_1 type. $\{c\}$
- Objects-of targets: $\geq_1 p^-$. \top
- Subjects-of targets: $\geq_1 p$. T



Provenance & Neighborhoods

- Our goal: Provide **provenance** of a shape schema
 - → explains **why** the graph conforms
- Provide a subgraph of the data that is relevant

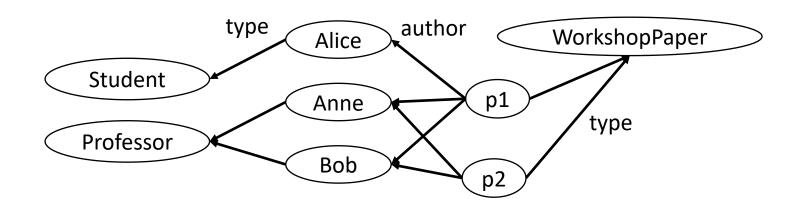
Neighborhood: $B(G, v, \phi)$

- G a graph
- *v* a node
- ϕ a shape

What part of G is relevant to decide that v satisfies ϕ in G?



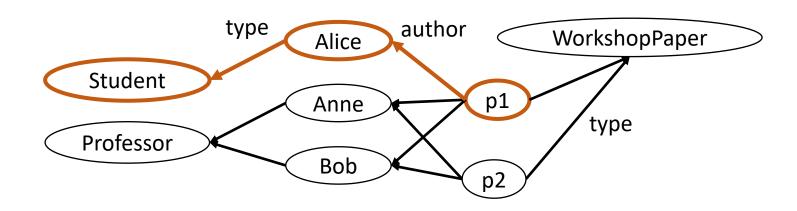
Neighborhood example



Workshopshape $\leftarrow \geq_1$ author. \geq_1 type.{Student}

B(G, p1, Workshopshape)

Neighborhood example



Workshopshape $\leftarrow \geq_1$ author. \geq_1 type.{Student}

B(G, p1, Workshopshape)

Shape Fragments

... as an application of neighborhoods.

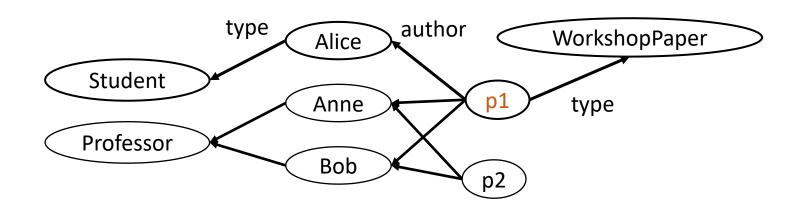
We define Frag(G, S) as the union of all neighborhoods of nodes satisfying the shapes from S in G.

Let *H* be a shape schema, we define:

$$Frag(G, H) := Frag(G, S)$$

where $S = \{ \phi \land \tau \mid \tau \text{ is the target of } \phi \text{ in } H \}$

Shape Fragment example

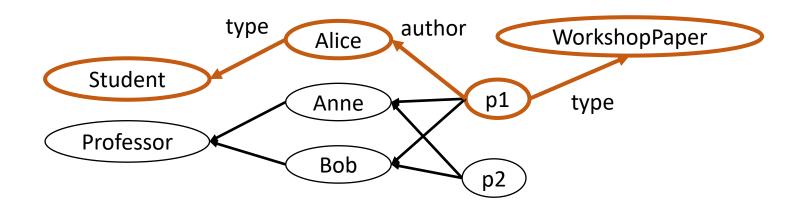


Let H be the schema:

Workshopshape $\leftarrow \geq_1$ author. \geq_1 type.{Student}

 \geq_1 type. {WorkshopPaper} \subseteq Workshopshape

Shape Fragment example



Let *H* be the schema:

Workshopshape $\leftarrow \geq_1$ author. \geq_1 type.{Student} \geq_1 type.{WorkshopPaper} \subseteq Workshopshape $= \operatorname{Frag}(G, H)$

Correctness properties

We have established:

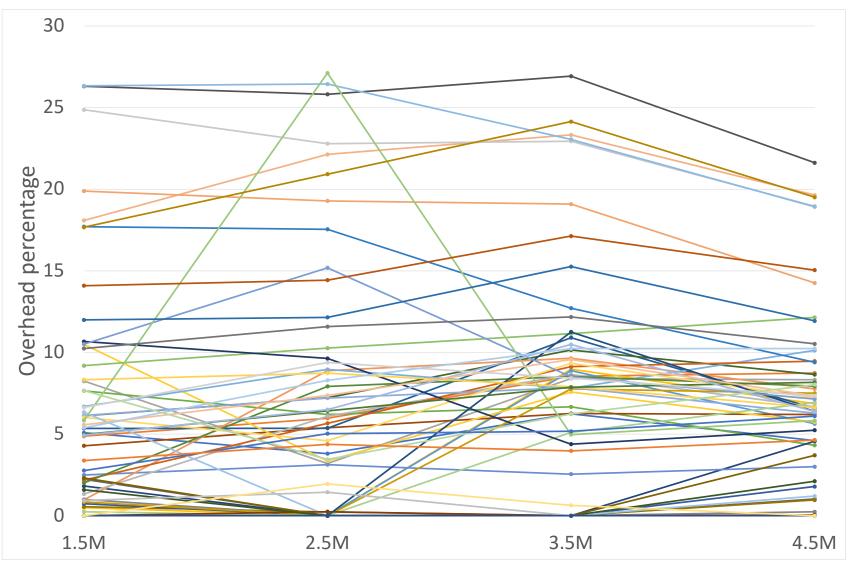
Sufficiency Theorem. If a node v satisfies a shape ϕ in a graph G, then: v also satisfies ϕ in G' for any subgraph $G' \subseteq G$ s.t. $B(G, v, \phi) \subseteq G'$.

Conformance Theorem. If a graph G satisfies a schema H, then: Frag(G, H) also conforms to H.

Tools

- PySHACL implementation
- Translation to SPARQL
 - Conformance queries
 - Neighborhood queries

PySHACL overhead

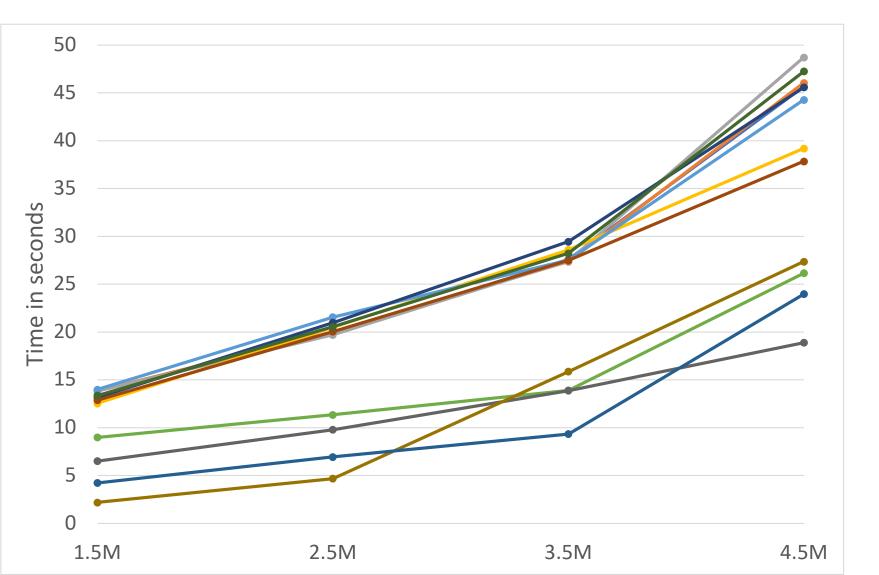


- 56 shapes
- $1.5 \rightarrow 4.5$ M triples

• Average: 10%

• Average $\geq 1s$: 15,6%

SPARQL query run time



- 13 shapes
- $1.5 \rightarrow 4.5$ M triples

Paths

SHACL supports (regular) path expressions:

$$E := p \mid p^- \mid E \cup E \mid E/E \mid E^* \mid E?$$

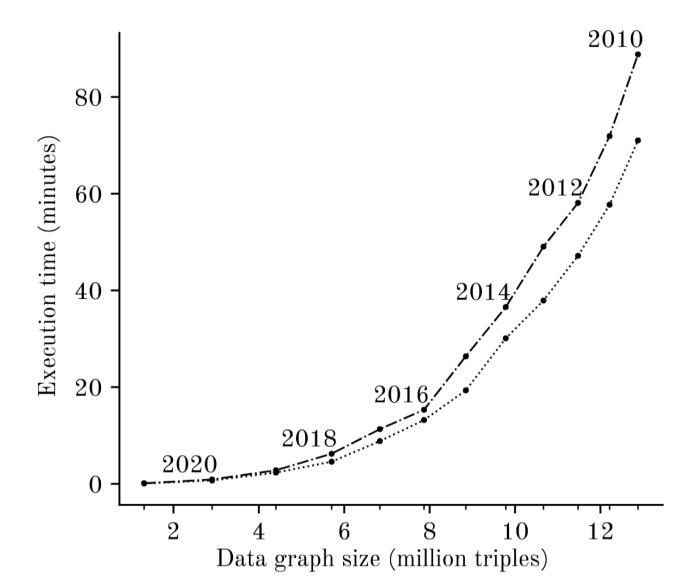
The neighborhood collects all triples on a path.

Example:

$$\geq_1 a^-/a/a^-/a/a^-/a.\{MYV\}$$

→ retrieves all authors of distance 3 from {MYV}, **and** all triples on that path.

Path shape with SPARQL



- Executed on DBLP RDF data
- Run on two SPARQL engines:
 - Jena ARQ (dotted)
 - GraphDB (dashed)

Conclusion & Open Problems (1)

- There are many different 'reasonable' ways to define subgraphs from a shape
- Different definitions have different properties

- Sufficiency is a well-known property
- What properties can a subgraph have?
 - ... e.g., can we define subgraphs that are minimally sufficient and unique?

Conclusion & Open Problems (2)

- Optimizing generated SPARQL queries
 - Conformance checking
 - Neighborhood extraction